

Using DISCOVER-AQ and KNMI NO₂-sonde data for OMI validation

City-Sonde Science

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KNMI NO2-Sonde: Instrument Overview

Runtime: reservoir dependent (hours to days)

• Sampling: 1 second

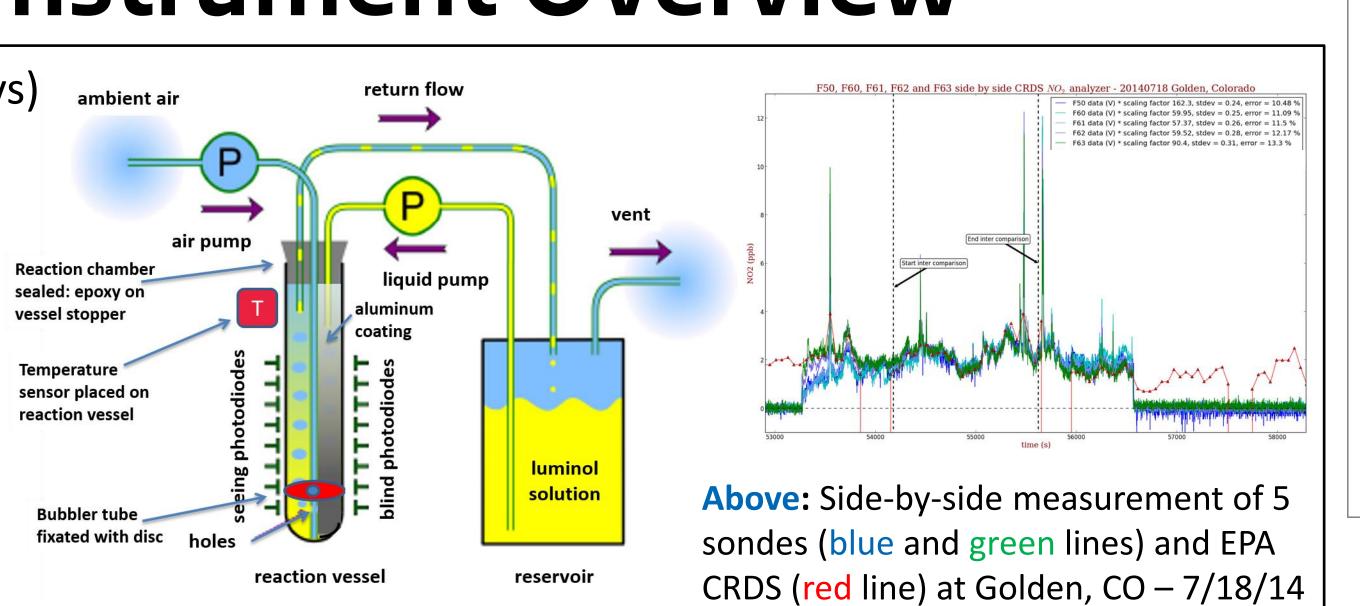
Accuracy: +/- 1 ppbv

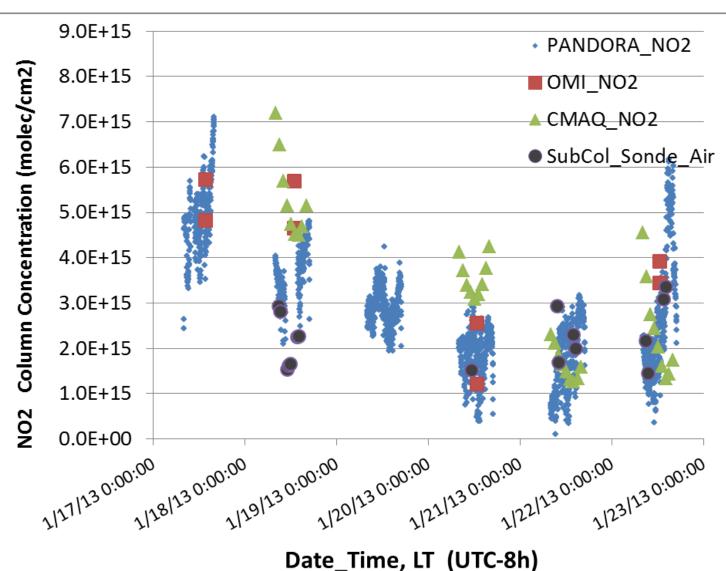
• **Range:** 1-100 ppbv

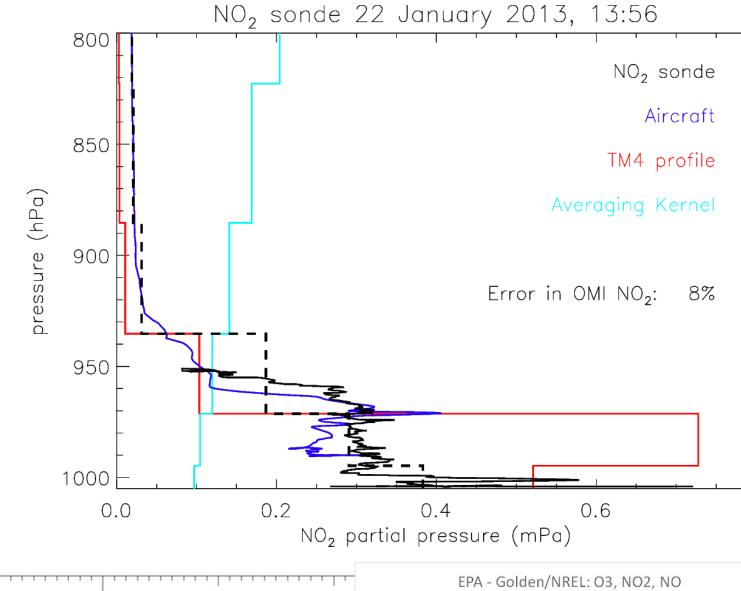
• Method: Chemiluminescence

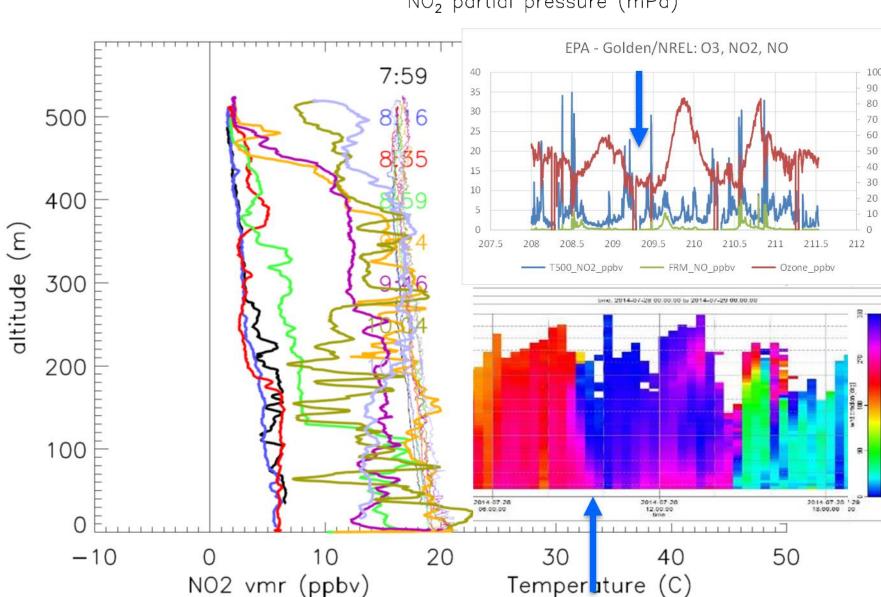
 Deployment: lightweight, weather balloon, tethered balloon, aircraft, UAV, mobile lab,

ground stations, bicycle





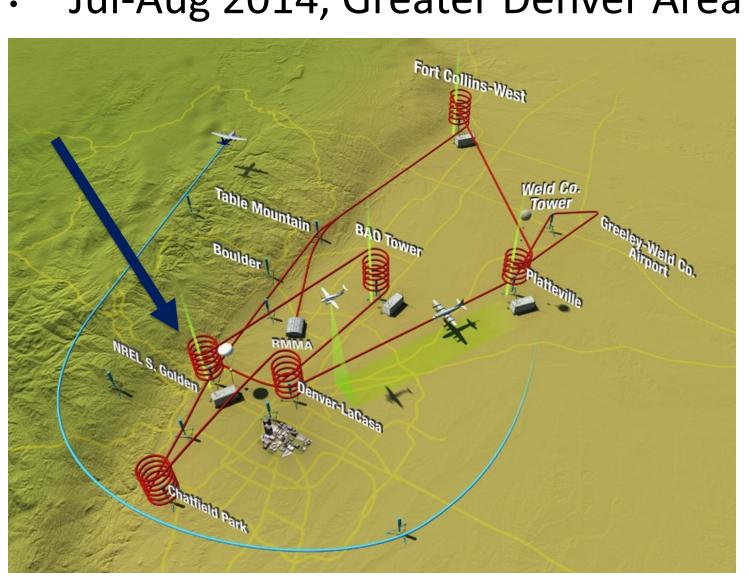


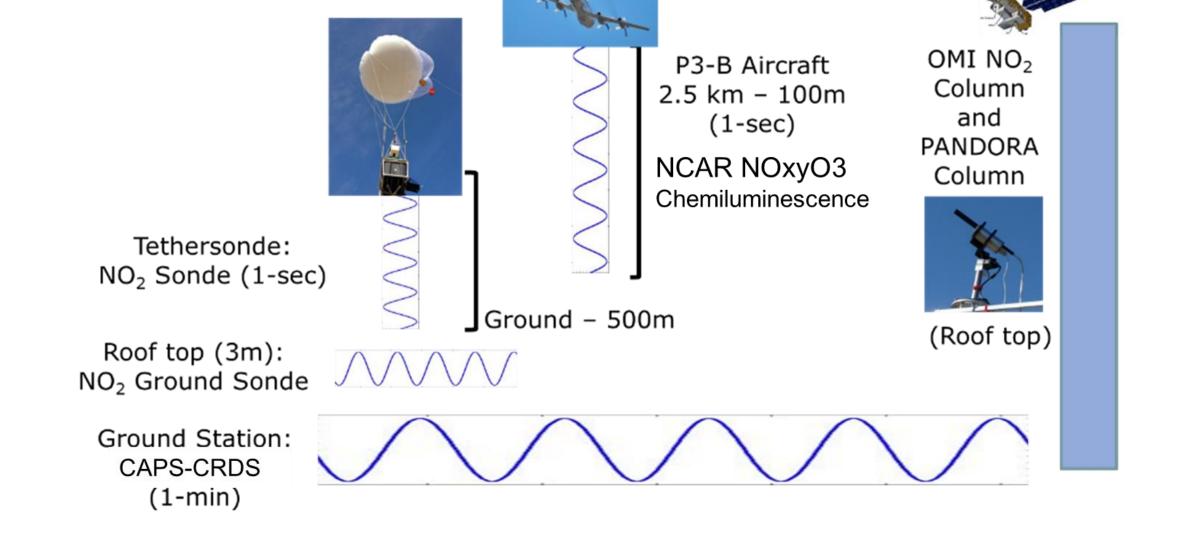


DISCOVER-AQ: Campaign Participation

Campaign Dates and Locations:

- July 2011, Baltimore/Washington DC
- Jan-Feb 2013, Central California
- Sep 2013, Greater Houston Area
- Jul-Aug 2014, Greater Denver Area





Above: Typical measurement setup at DISCOVER-AQ site for NO₂-sonde Left: Overview of DISCOVER-AQ measurement network, Colorado 2014 Right: Top two panels comparison of column and profile measurements from sonde, aircraft, model and retrieval, bottom panel NO₂-sonde profiles from Golden, CO during Denver Cyclone event, 28 July 2014

City-Sonde Science: 1 year and counting



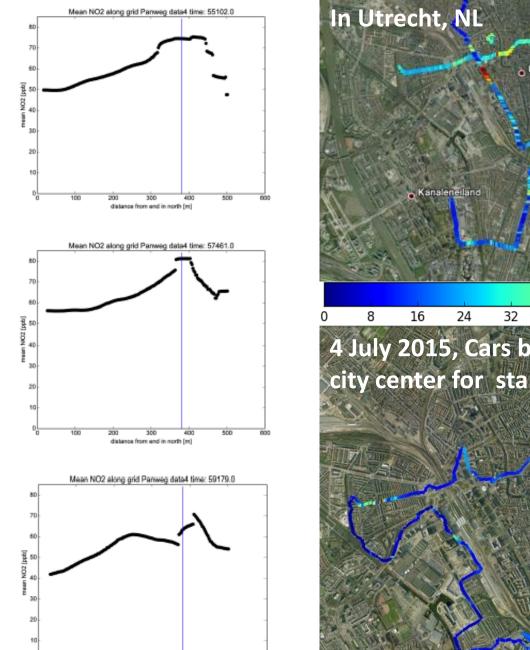


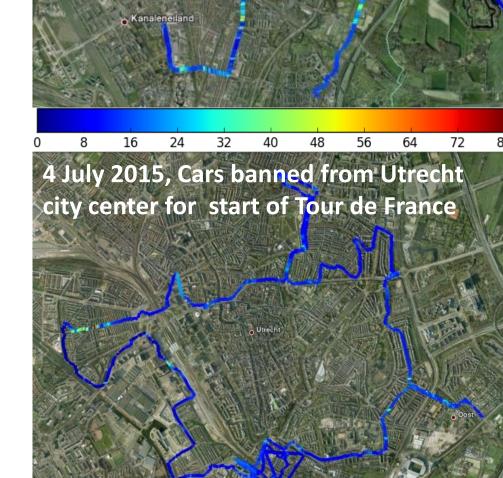
Weather Station with GPS module + Bicycle platform

 Campaign: More than 400 hours of measurements from over 20 volunteers; Mostly on weekdays during morning and evening rush hour; Case studies aimed at finding NO₂ hotspots

• Validation?: Not directly, but the high resolution data (~5m) from this type of measurement is well-suited for studying intrapixel variability, especially TROPOMI (7 x 7 km, 3.5 x 7 km)

Highway gradients near KNMI and detailed city maps of Utrecht: Highway gradients plotted by E. Tenner (CSS Student)





Current and Future Activities:

CINDI-2, Sep 12-Oct 7, 2016 in Cabauw, NL

- Initialization of European FRM4DOAS network instrumentation
- Comparison with small sensors for mobile and stationary measurements focusing on horizontal variability

Future ESA Romania Validation Campaigns 2017 – 2018

- Building on campaigns in 2014 and 2015, validation for TROPOMI using aircraft and NO2-sonde launches

Future TROPOMI Campaign in Cabauw, NL Spring 2018

- Validation for TROPOMI Sentinel-5 Precursor focused on error characterization for mixed cloud conditions

Why Romania?

More opportunity for (TROP)OMI validation Bucharest

intoi joivii validatioii								
Location	Overpasses	CRF < 50 %	Row Anom.	dist < 30 km	OPS left (%)	Trop. VC	Err. Trop. VC	Error %
Bremen	72	18	18	15	20.8	6.3	4.0	64.0
Bucharest	58	41	41	32	55.2	3.2	1.7	53.1
De Bilt	74	14	14	13	17.6	8.0	4.3	54.4
Mainz	68	7	7	5	7.4	8.5	4.5	52.9
Turceni	64	38	35	31	48.4	2.2	1.8	79.3
Heele	67	14	42		12.4	7.0	4.0	60.3

Above: Table summarizing percentage of remaining observations (OPS left) after filtering for cloud cover and OMI row anomaly, for Aug-Sep 2014;

Bucharest and Turceni, consistently have more coverage than other northern European sites

Left: Comparison of remaining OMI NO2 (DOMINO) data remaining after filtering for CRF < 50% and row anomaly based on overpass files for 4 European sites (temis.nl)

Results from the AROMAT campaign team: including Alexis Merlaud (BIRA-IASB) & Mirjam den Hoed